

# Ontology Driven Adaptive Data Processing In Wireless Sensor Networks\*

Work-in-progress

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## ABSTRACT

It is important to provide adaptive data processing in wireless sensor networks in order to deal with various applications. In this paper, we propose a Wireless Sensor Networks Ontology (WISNO) for flexible modeling of sensor data. WISNO contains two-tier ontologies, a front-end for coarse-grained analysis and a back-end for high-level fine-grained data processing. We also describe the WISNO reasoning rules that adopt description logic and SWRL for managing data automatically.

## Categories and Subject Descriptors

C.2.3 [Computer-Communication Networks]: Network Operations—*Network management*

## General Terms

Management, Performance

## Keywords

Wireless Sensor Networks, Ontology, SWRL, description logic

## 1. INTRODUCTION

With the development of sensor networks, an adaptive strategy for sensor-data processing and management is needed. Ontology is widely used to enrich data description, which facilitates data processing and management. Most of the current research focuses on how to use the single ontology to model data and load the sensor data into a knowledge base for subsequent application. However, merging huge volume

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of sensor data and deliver them to the end-user would cause high communication cost and processing cost.

We propose a two-tier ontology driven framework WISNO for flexible data processing in wireless sensor networks. In this framework, the front-end performs lightweight reasoning at the sensor nodes for coarse-grained analysis and regulating data stream. This fits well with the resource-limited sensor nodes. The back-end performs deep data analysis at high-performance servers. We adopt Description Logic to enable context classification and comparison at the front-end, while SWRL [1] is used to encode specific rules according to different contexts of spots.

## 2. APPLIED SCENARIO

We propose our scenario (Figure 1) that uses WISNO to merge and manage the data. Specifically, the front-end is responsible for capturing environmental data and coarse-grain analysis, whereas the back-end takes charge of further data analysis by heavyweight reasoning and issuing high-level actions.

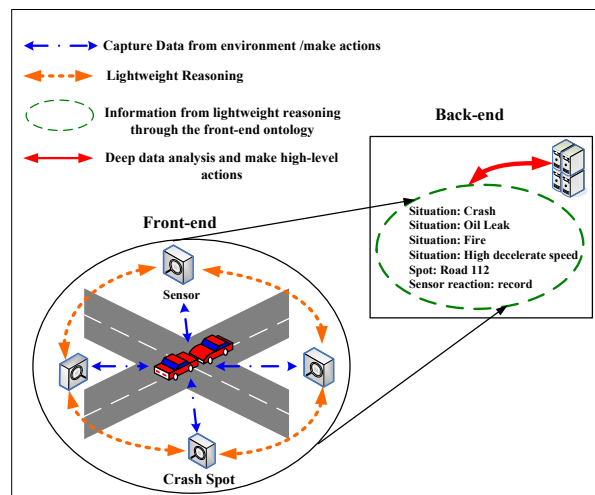
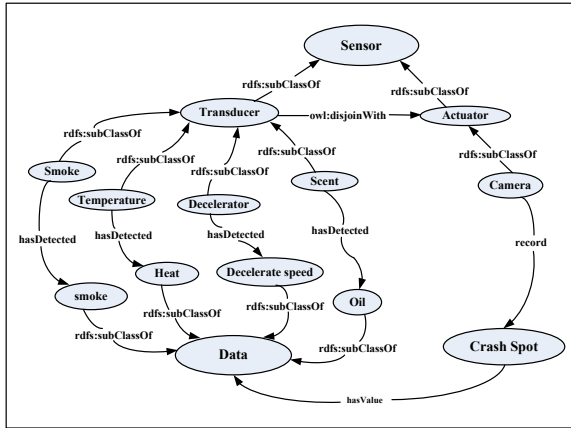


Figure 1: Crash demo in WSN

## 3. THE PROPOSED ONTOLOGY

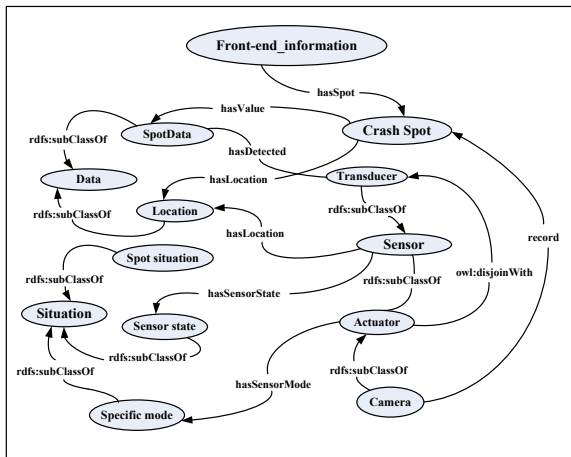
WISNO is a Semantic Web compatible ontology devel-

oped using Protege<sup>1</sup>. Currently, the front-end ontology (Figure 2) provides some fundamental concepts, e.g. sensor, location, and spot situation as well as a set of sub-classes to collect basic features of environmental context.



**Figure 2: Partial definition of specific ontology for Front-end**

The back-end (Figure 3) contains the front-end concept imported by `<owl:imports>` syntax and collection of detailed sensor properties, e.g. sensor energy capacity and sensor state to improve precision of reasoning.



**Figure 3: Partial definition of specific ontology for Back-end**

WISNO deviates from SensorML [2] since it lacks the semantic richness for inference. In addition, we extracted the commonly used terms in sensor domain from IEEE 1454.1 smart transducers template description language[3].

## 4. CONTEXT REASONING

The context reasoning in WISNO has two main usages: deducing high-level, explicit information from low-level, implicit context, and checking the consistency of ontologies.

<sup>1</sup><http://protege.stanford.edu/>

Sensor data and properties are treated as instances of concepts defined in front-end or back-end.

### 4.1 Front-end Reasoning

The mission of front-end reasoning is to evaluate data and determine whether it needs to be send for further analysis in back-end.

We adopt DL as the foundation of inference. DL approaches integrate powerful inference mechanisms to reason on the schema, the reasoner computes the concepts instances belong to by determining whether instances satisfy the constraint.

Table 1 shows a DL rule related to the crash scenario depicted in Section 3. We assume a crash by: 1)high decelerate speed with 2) oil leakage on road and 3)fire in the spot.

**Table 1: Front-end rules for situation**

Front-end Reasoning Rules
Crash $\equiv \exists$ has_Detected.Oil_Leak $\sqcap \exists$ has_Detected.Fire $\sqcap \exists$ has_Detected.Decelerate_Speed

### 4.2 Back-end Reasoning

In back-end reasoning, we load additional sensor properties, (e.g location, states) with data from front-end into heavyweight inference for deep data analysis and sensor controls.

Table 2 shows one of the rules for getting and setting sensor state: the camera sensor changes its working mode to infrared mode when fire detected.

**Table 2: Back-end heavyweight reasoning rules**

Back-end Reasoning Rules
$(?camera \text{ getSensorState } \text{working}) \wedge (?spot \text{ has\_spot } \text{Fire}) \Rightarrow (?camera \text{ setSensorMode } \text{Infred\_Mode})$

## 5. CONCLUSION AND FUTURE WORK

Our study in this paper shows the WISNO framework is feasible for supporting adaptive data-processing in WSN. Currently, we are working on implementing a prototype using Pellet<sup>2</sup> to reason about ontologies and Jess<sup>3</sup> for reasoning about rules, both accessed through Jena<sup>4</sup> API. As for future work, we plan to test effectiveness of WISNO by quantitatively measuring the reaction speed in a real environment.

## 6. REFERENCES

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- [3] C. H. Jones. IEEE 1451.4 smart transducers template description language, <http://standards.ieee.org/regauth/1451> accessed/Tutorials.html, April22, 2006.

<sup>2</sup><http://www.mindswap.org/2003/pellet>

<sup>3</sup><http://herzberg.ca.sandia.gov/jess>

<sup>4</sup><http://jena.sourceforge.net/>