

# Graphical Solutions of Fuzzy Models

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**Abstract.** In the knowledge of dynamical system Fuzzy Initial Value Problems (FIVPs) have been vigorously investigated over the modeling of numerous exhilarating actual world problems with all branches of engineering and science. In this paper, numerical solution is associated with (1)gh and (2)gh differentiability. We propose a fuzzy version of Picard's Method, solutions in linear fuzzy differential equations with first-order. The proposed technique is exemplified by a real-life sample and found to be in good agreement. The efficiency and accuracy of the suggested technique is demonstrated in a series of graphical representations.

**Keywords:** Fuzzy Number, Generalized differentiability, Fuzzy initial value problem, Fuzzy Picard's method.

## 1 Introduction

Fuzzy Picard's method is an iterative technique for finding solutions of fuzzy difference equation through successive approximations. It is used for transforming fuzzy linear differential equation to integral equation. The solution of this method gives accurate results for fuzzy linear differential equations as it uses the same step size and degrees of precision in the integration procedure. The Picard's existence and uniqueness theorem is used for higher instruction fuzzy differential equation and also for systems of simultaneous fuzzy differential equation. The fuzzy Picard's process resembles that of Fuzzy Taylor's expansion. The  $n$ th approximation is added to integral equation and is used for computation of  $(n + 1)$ th element of the sequence.

Sadigh Behzadi [1] and others received the Picard technique for addressing the Painlevé I and quadratic Riccati conditions below fluffly climate and summed up  $H$  differentiability. Sindu Devi. S and K Ganesan [2] suggested iterative plan arrangement of additional request fluffly differential conditions fluffly beginning condition utilizing fluffly picard strategy under summed up  $H$  – differentiability. Ettoussi, S et.al [3] has examined to discover the force arrangement of an intuitionistic fluffly introductory worth issues by utilizing progressive estimate strategy and we demonstrate that the rough arrangement combine consistently in  $t$  to the specific arrangement. Hussein ALKasasbeh et.al [4] have proposed new guess techniques for tackling frameworks of common differential conditions (SODEs) by fluffly change (FzT). A class of Volterra integro-differential conditions, has been stretched out to tackle issues including Caputo fluffly fragmentary differential conditions Picard-like [numerical conspire by, Jorge E. Macias-Diaz [5]. and Stefania Tomasiello

In this article, we introduce first order fuzzy differentials equation under (i) – gh and (ii) – gh differentiability using fuzzy Picard’s technique being with individuality solutions set satisfies the given system with a certain possibility. It shown that at anytime the solution constitutes a fuzzy region and alpha-cuts in the graphical representation.

## 2 Preliminaries

This segment contains some elementary definition which is very useful throughout this paper.

**Definition 2.1.** “Fuzzy set  $\tilde{a}$  clear real number  $R$  supposed fuzzy number association functions  $\tilde{a}: R \rightarrow (0,1)$  succeeding:

- i.  $\tilde{a}$  are convex, i.e.,  $\tilde{a}\{\lambda x_{1-0} + (1 - \lambda)x_2\} \geq \min\{\tilde{a}(x_1), \tilde{a}(x_2)\}$ , for all  $x_1, x_2 \in R$  &  $\lambda \in [1,0]$
- ii.  $\tilde{a}$  are regular i.e., occurs an  $x \in R$  such  $\tilde{a}(x) = 1-0$
- iii.  $\tilde{a}$  are piece-wise continuous

**Definition 2.2.** “A triangular fuzzy number is denoted as  $\tilde{a} = (a_1, a_2, a_3)$  and is definite by the membership function

$$\tilde{a} = \begin{cases} 0, & x \leq a_1, \\ \frac{x - a_1 - 0}{a_2 - a_1}, & a_1 \leq x \leq a_2, \\ \frac{a_3 - x}{a_3 - a_2}, & a_2 \leq x \leq a_3, \\ 0, & x \geq a_3. \end{cases}$$

### 2.1. Parametric Representation of fuzzy numbers.

A fuzzy number  $\tilde{a} \in F(R)$  also signified duo  $\tilde{a} = (\underline{a}, \bar{a})$  of function  $\underline{a}(\alpha)$  and  $\bar{a}(\alpha)$  for  $0 \leq \alpha \leq 1$  contents the subsequent requirement:

- i.  $\underline{a}(\alpha)$  is a circumscribed monotonic cumulative increasing functions.
- ii.  $\bar{a}(\alpha)$  is a circumscribed monotonic lessening leftward increasing functions.
- iii.  $\underline{a}(\alpha) \leq \bar{a}(\alpha)$ ,  $0 \leq \alpha \leq 1$ .

## 3 Fuzzy Derivative

**Definition 3.1.** [Hukugara Derivative] Deliberate a fuzzy mapping  $F: (a, b) \rightarrow R$  and  $t_0 \in (a, b)$ .  $F$  is differentiable  $t_0 \in (a, b)$  if exist element  $F'(t_0)$   $Rh > 0$  adequately slight  $\exists F(t_0 + h) \ominus F(t_0), F(t_0) \ominus F(t_0 - h)$  limit  $D$

$$\lim_{h \rightarrow 0+} \frac{F(t_0 + h) \ominus F(t_0)}{h} = \lim_{h \rightarrow 0-} \frac{F(t_0) \ominus F(t_0 - h)}{h}$$

exists and are equal to  $F'(t_0)$ .

### Fuzzy Initial Value Problem

initial value problem is a systems of usual differential equation together with the first conditions. Consider a function of  $n^{th}$  fuzzy differential equations initial complaint are

$$\begin{aligned} \tilde{y}^n(t) &= \tilde{f}(t, y(t), y'(t), \dots, y^{n-1}(t)) \\ \tilde{y}(t_0) &= y_0, \dots, \tilde{y}^{n-1}(t_0) = y_0. \end{aligned}$$

By using Extension principle, the membership functions are

$$[\tilde{f}(t, \tilde{y})]^\alpha = \tilde{f}(t, [\tilde{y}]^\alpha) = \tilde{f}\left(t, \left[\underline{y}_\alpha, \tilde{y}_\alpha\right]\right) = \left(\min \tilde{f}\left(t, \left[\underline{y}_\alpha, \tilde{y}_\alpha\right]\right), \max \tilde{f}\left(t, \left[\underline{y}_\alpha, \tilde{y}_\alpha\right]\right)\right)$$

#### 4 Analysis of the method:

In this segment, we exemplify the idea of the method. Let us deliberate the subsequent overall difference equations.

$$y'(t) = u(t, y). \quad \tilde{y}(t_0) = y_0$$

Alteration of variables to alter the original condition to the origin. Openly, describe  $w = y - y_0$  and  $x = t - t_0$ . With a new  $f$ , the differential equations is

$$y'(t) = u(t, y). \quad \tilde{y}(0) = 0$$

$$y_{n+1}(t) = y_n(s) + \int_0^t (f(s, y(s))) ds$$

we relate the picard technique for (i) – gH differentiability

$$\begin{cases} u_{n+1}(t, \alpha) = u_n(s, \alpha) + \int_0^t f(s, u_n(s, \alpha)) ds, \\ u_{n+1}(t, \alpha) = u_n(s, \alpha) + \int_0^t f(s, u_n(s, \alpha)) ds. \end{cases}$$

we relate the picard technique for (i) – gH differentiability

$$\begin{cases} u_{n+1}(t, \alpha) = u_n(s, \alpha) - \int_0^t f(s, u_n(s, \alpha)) ds, \\ u_{n+1}(t, \alpha) = u_n(s, \alpha) - \int_0^t f(s, u_n(s, \alpha)) ds. \end{cases}$$

**Example 1:** Solve  $y' = -y + t + 1$ . with initial conditions  $y(0) = (0.96, 1, 1.01)$  then find the solution at  $t = [0, 1]$ .

$$\text{Use (i) – gh differentiability} \begin{cases} u_{n+1}(t, \alpha) = u_n(s, \alpha) + \int_0^t f(s, u_n(s, \alpha)) ds, \\ u_{n+1}(t, \alpha) = u_n(s, \alpha) + \int_0^t f(s, u_n(s, \alpha)) ds. \end{cases}$$

$$\text{and (ii) – gh differentiability} \begin{cases} u_{n+1}(t, \alpha) = u_n(s, \alpha) - \int_0^t f(s, u_n(s, \alpha)) ds, \\ u_{n+1}(t, \alpha) = u_n(s, \alpha) - \int_0^t f(s, u_n(s, \alpha)) ds. \end{cases}$$

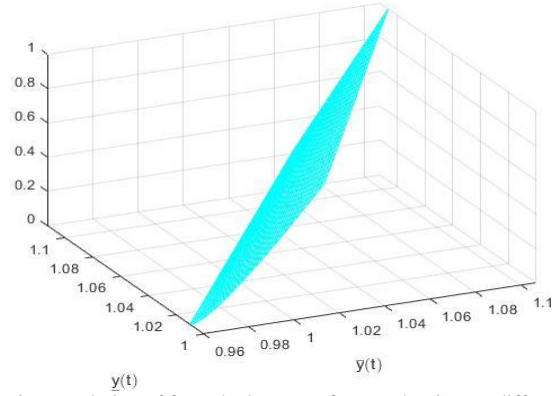


Figure 1: Approximate solution of fuzzy laplace transform under (i) –gH differentiability.

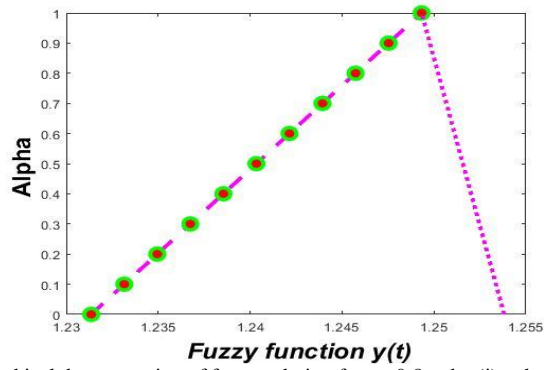


Figure 2: Graphical demonstration of fuzzy solution for  $t = 0.8$  under (i) –gh differentiability.

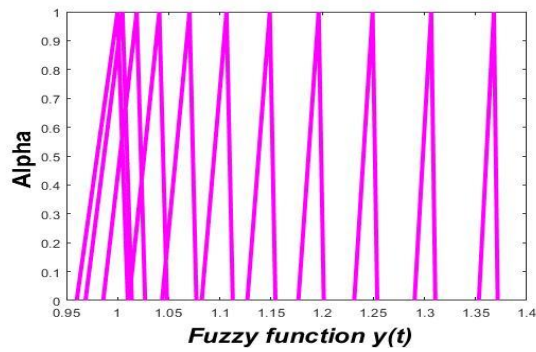


Figure 3: Graphical demonstration of fuzzy solution for  $t = 0, 0.1, 0.2, \dots, 1$  at fifth approximation under (i) –gh differentiability.

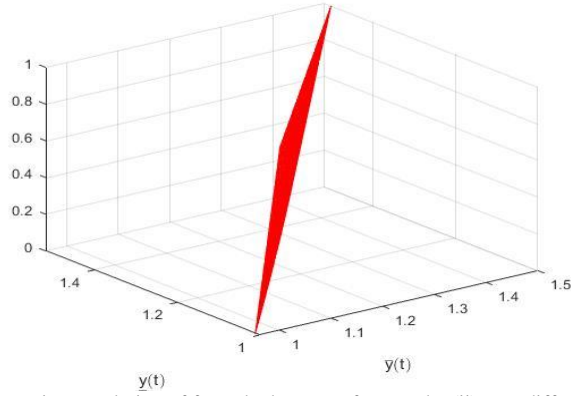


Figure 4: Approximate solution of fuzzy Laplace transform under (ii)-gH differentiability.

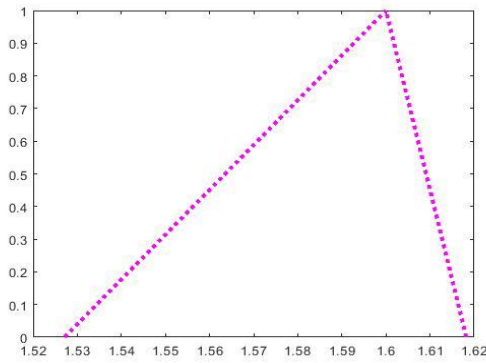


Figure 5: Graphical demonstration of fuzzy solution for  $t = 0.8$  under (ii)-gH differentiability.

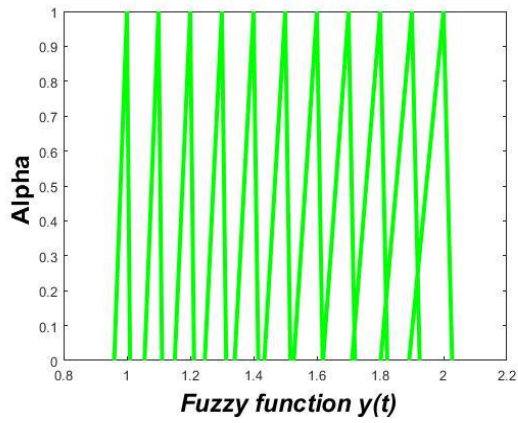


Figure 6: Graphical demonstration of fuzzy function  $y(t)$  for  $t = 0, 0.1, 0.2, \dots, 1$  under (i)-gH differentiability.

**Example 2:** A tank at first contains 300 lbs of saline solution disintegrated in  $c$  lbs of salts. Approaching the cistern at 3 lbs/min is brackish water with focus  $k$  lbs salts very much mixed combination greeneries rate 3 lbs/min. Let  $y(x)$  lbs be the salt in tanks at any time  $t \geq 0$ . At that point  $dy(x)/dx + (1/100)y(x) = k$ ,  $x \in [0,1]$  with  $y(0) = c$ , if underlying disorder is existence displayed as fluffy number  $c = (1,2,3)$  and  $k = (1,2,4)$ . Discover arrangement  $x = 0.4$ . The below figures shows the approximate solutions of (i)-gh and (ii)-gh differentiability

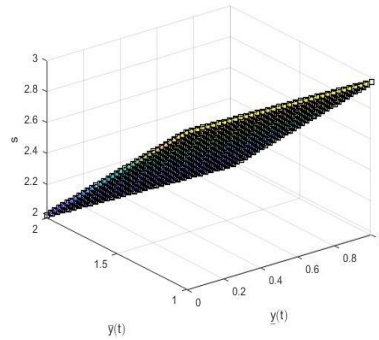


Figure 7: Approximate Solution of Fuzzy Picard's method under (i)-gh differentiability.

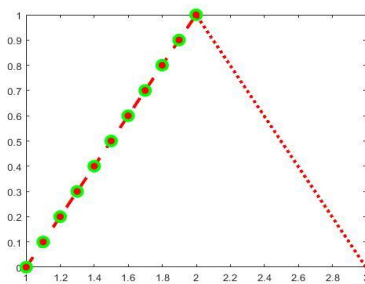


Figure 8: Graphical demonstration of fuzzy solution for  $t = 0.1$  under (i)-gh differentiability.

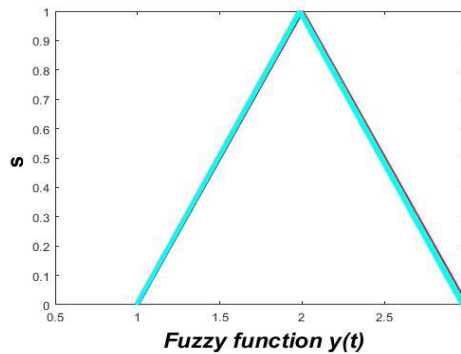


Figure 9: Graphical demonstration of fuzzy solution for different values  $t = 0, 0.1, 0.2, \dots, 1$  at fifth approximation under (i)-gh differentiability

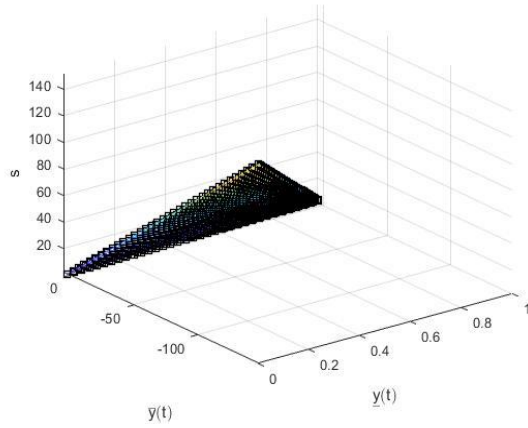


Figure 10: Approximate Solution of Fuzzy Picard's method under (ii) -gH differentiability.

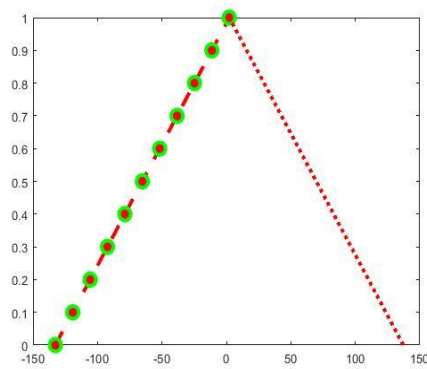


Figure 11: Graphical demonstration of fuzzy solution for  $t = 0.1$  under (ii) -gH differentiability.

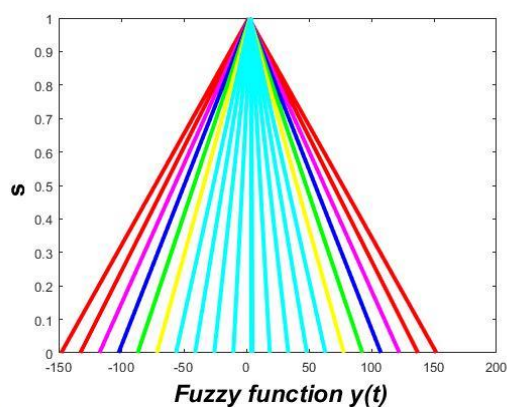


Figure 12: Graphical representation of fuzzy solution for dissimilar values  $t = 0, 0.1, 0.2, \dots, 1$  under (ii) -gH differentiability.

## Conclusions

In this article, we have discussed Picard's technique for first order fuzzy differential equation proved under (i) – gh and (ii) – gh differentiability. For the efficacy of the suggested technique demonstrated by generous example, in the upcoming investigation relate the Picard technique to resolve a great class of FDEs.

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