Recommendation with quantitative implication rules

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Abstract

Association rules based recommendation is one of approaches to develop recommendation systems. However, such systems just focus on binary dataset, whereas many datasets are in the quantitative form. There are many solutions proposed for this problem such as combining the association rules mining with fuzzy logic, binarizing quantitative data, etc. These proposals have contributed to improving the performance of traditional association rules mining, however, they have to deal with the trade-off between the processing performance and the loss of information. In this paper, we propose a new approach to make recommendations based on implication rules. The experimental results show that our proposed solution can be implemented on quantitative dataset well as well as improve the accuracy and performance of the recommendation systems.

Keywords: association rules, implication rules, quantitative dataset, recommendation.

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1. Introduction

The objective of the recommendation systems [1] [6] is to filter useful information from a large amount of information so that it can predict the rating given by an active user for an item, and recommend the suitable items to that user. Because of the rapid increase of data in era of information explosion, recommendation systems are more necessarily and widely used by e-commerce and services companies to raise their revenue and attract customers, as well as help users find items matching their interests.

Association rule mining (ARM) algorithms [2][25] have attracted the attention of researchers and are applied in collaborative filtering recommendation systems [4][28]. Most of ARM algorithms are based on traditional framework using the support and confidence measures for generating rules [2][17]. Those algorithms filter information and then recommend the suitable items to users, and just focus on the binary or two-valued categorical data. Finding association rules on binary or two-valued categorical data has been well researched and documented [2][16][18][19][20]. However, in practice, data sets are not only binary form but also quantitative form.

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The ARM algorithms using the traditional framework is based on conditional probability (support and confidence) [18][19][20] to select useful rules. However, the confidence of a rule $A \rightarrow B$, where A, B is an itemset (set of variables), is unchanged when the size of B or E (the population) changes; and is not sensitive to the expansion of the size of A and *B* because the confidence measure ignores the frequency of occurrence of *B* and *E* [7]. On the other hand, rule $A \rightarrow B$ is more likely to occur when the size of B increases or when the size of E decreases; and moreover this would make more sense when the size of all sets grows in the same proportion. To overcome this limitation of the confidence measure, it usually uses the lift measure. However, lift [24] is a measure of symmetry, it is not possible to distinguish the reversible rules (which will have the same lift value). Besides, the lift measure is easy to noise in the small database. Rare items with low probability, incidentally occurring several times (or only once) together, can generate the high lift values. In additional, support is declined rapidly with the itemsets size [16] and defining the support and confidence thresholds is a challenge for users. In fact, these values are chosen to generate the number of itemsets or rules that can be regularly managed. Therefore, there are the risks and costs associated with the use of fraudulent or less significant rules in an



application when the minimum support is too small, or there is a lack of significant rules if these values are too big.

Many studies have proposed the improvement of ARM algorithms for quantitative data such as using fuzzy logic [3][5][26][27], using techniques to transform the quantitative data to binary data [5][17][29]. Although these solutions solve the problem, they have to trade-off between the performance and the accuracy of algorithm as well as the information loss problem.

Statistical implication analysis (SIA) theory [22], proposed by Regis Gras, studies the implication relationships of data variables (items) which can be considered as association rules. Therefore, SIA can be applied for building recommendation systems. The studies in [9] [10] [11] [12] [13] [14] [17] proposed the recommendation models based on SIA, but they just focus on the binary data.

In this paper, we propose a new approach to make recommendations which uses implication rules in the implication field to improve the accuracy and the performance of recommendation systems for both binary and quantitative datasets.

The paper is organized in six parts. The first one introduces the context and issues to be solved by the present recommendation systems as well as proposes our approach. The second part presents the content related to SIA measures and the implication field. The third part is about association rules and implication rules. The fourth part depicts the recommendation model based on the variance of the implication index in the implication field. The next part is the experiment. Finally, the last part is the conclusion.

2. Implication field

2.1. Statistical implication analysis

SIA uses measures such as implication index and implication intensity to detect the strong implicative relationships among variables (properties, attributes, items) (i.e. detect the rules with the strong implication between two sides of rule). In addition, statistical implication analysis focuses on the counter examples analysis.

SIA can be presented as Figure 1 [21][22]. For binary variables, let E be the population of n objects or individuals described by a finite set of variables; A(B) be the subset of E containing the object *i* such that A(i) = true (B(*i*) = *true*); sets \overline{A} , \overline{B} be the complement of set A and B respectively; $n_A = card(A)$, $n_B = card(B)$ be the cardinality of A and B respectively; $n_{\bar{A}} = card(\bar{A})$ and $n_{\bar{B}} = card(\bar{B})$ be the cardinality of the set \overline{A} and the set \overline{B} respectively; and $n_{A\overline{B}} =$ $card(A \cap \overline{B})$ be the cardinality of the set $A \cap \overline{B}$ containing the objects that satisfy the properties A but does satisfy the properties B, $n_{A\bar{B}}$ is also called counter-example. For quantitative variables, $n_A = \sum_{i=1}^n A(i)$, $n_{\bar{B}} = \sum_{i=1}^n (1 - 1)$ B(i); A(i) is the value given by object *i* for set A; B(i) is the value given by object *i* for set B; and $n_{A\bar{B}} = \sum_{i=1}^{n} (A(i) * (1 - \sum_{i=1}^{n} (A(i) + \sum_{i=1$ B(i)). The implication relationship between two variables A and B (A \rightarrow B) is presented by 4 parameters (n, n_A, n_B, n_{A\overline{B}}).



Figure 1. The Venn diagram of the SIA presentation.

For example, with two datasets of 9 objects described by 3 variables as Figure 2, the implication relationship between two variables (movies) Toy Story (1995) \rightarrow Star War (1997) is (9, 5.2, 7.8, 0.72) if variables are in the quantitative form and (9, 7, 8, 1) if variables are in the binary form.



Figure 2. Demonstration of statistical implication relationships: $(A \rightarrow B) = \{n, n_A, n_B, n_{A\overline{B}}\}.$

2.2. Family of implication measures

The SIA's measures are asymmetric. Unlike other data analysis methods, SIA is based on counter-examples, the smaller the counter-example is, the greater the degree of the implication relationship is and vice versa. Two important measures of SIA are the implication index and the implication intensity.

Implication intensity measure $\varphi(A, B)$ of rule $A \rightarrow B$ is defined by (1) [22]:

$$\varphi(A,B) = \begin{cases} \varphi(A,B) = \\ \left\{ 1 - \sum_{s=0}^{n_{AB}} \frac{\lambda^s}{s!} e^{-\lambda} = \frac{1}{\sqrt{2\pi}} \int_{q(A,\bar{B})}^{\infty} e^{-\frac{t^2}{2}} dt , if n_B < n \end{cases} \end{cases}$$

$$(1)$$

where $\lambda = \frac{n_A n_{\bar{B}}}{n}$; and $q(A, \bar{B})$, called the implication index, is defined by (2a) if data is binary form and (2b) if data is nonbinary form.

When the approximation is justified (e.g. $\lambda \ge 4$), $q(A, \overline{B})$ is the approximation of the normal distribution N(0,1). The implication rule that $A \rightarrow B$ is admissible at the confidence level α if and only if $\varphi(A, B) \ge 1 - \alpha$ [22].

For binary variables, the implication index is defined by (2a) [22]:



$$q(A,\bar{B}) = \frac{n_{A\bar{B}} - \frac{n_A n_{\bar{B}}}{n}}{\sqrt{\frac{n_A n_{\bar{B}}}{n}}}$$
(2a)

For modal (nonbinary) variables, the implication index is defined by (2b) [22]:

$$q_p(A,\bar{B}) = \frac{\sum_{i \in E} A(i)\bar{B}(i) - \frac{n_A n_B}{n}}{\sqrt{\frac{(n^2 s_A^2 + n_A^2)((n^2 s_{\bar{B}}^2 + n_{\bar{B}}^2)}{n^3}}}$$
(2b)

where $n, n_A, n_{\bar{B}}$ are presented in Section 2.1; and $s_A, s_{\bar{B}}$ are the standard deviations of A and \bar{B} respectively.

This expansion is still valid for the frequency variable and quantitative variables when they are normalized by (3) [22].

$$\tilde{A}(i) = A(i)/max_{i \in E}A(i)$$
(3)

The relationship between the implication index and implication intensity is shown as (4).

$$\frac{d\varphi}{dq} = -\frac{1}{\sqrt{2\pi}}e^{-q^2} < 0 \tag{4}$$

This confirms that the implication intensity increases as q decreases. The rate of increase is determined by (6), which allows a more rigorous study of the variability of φ .

2.3. Implication field

Let us consider $n, n_A, n_B, n_{A\bar{B}}$ as four real variables satisfying the inequalities [22]: $0 \le n_A \le n_B$; $n_{A\bar{B}} \le \inf\{n_A, n_B\}$ and $\sup\{n_A, n_B\} \le n$. Let *M* be the point in the four-dimensional space R^4 whose coordinates are associated with *A* and *B*. The implication index $q(A, \bar{B})$ [21][22] is the function of four parameters $q(n, n_A, n_B, n_{A\bar{B}})$. In this case, *q* is a continuously differentiable function. The differential of q in Frechet's geometry is expressed in the following way [21]:

$$dq = \frac{\delta q}{\delta n} dn + \frac{\delta q}{\delta n_A} dn_A + \frac{\delta q}{\delta n_B} dn_B + \frac{\delta q}{\delta n_{A\bar{B}}} dn_{A\bar{B}} \qquad (5)$$

= dM.gradq

where dM is the differential component vector of the instance variables and grad.q is the partial differential vector of the variables.

 $q(A, \overline{B})$ is a scalar field by applying the mapping from space R^4 to space R. The vector *gradq* containing the partial derivatives of q for the variables $n, n_A, n_B, n_{A\overline{B}}$ is a gradient field. At each point of the gradient field, we observe an increase in the density of the implication in the space that changes under the influence of the transformation of one or more parameters. In this context, the gradient field is called the implication field. The mixed derivative event of each pair of variables [21], for example: $n_B, n_{A\overline{B}}$, is:

$$\frac{\delta}{\delta n_{A\bar{B}}} \left(\frac{\delta q}{\delta n_B} \right) = \frac{\delta}{\delta n_B} \left(\frac{\delta q}{\delta n_{A\bar{B}}} \right) \tag{6}$$

A plane of equipotential in implication field is curved in E, an 4-dimensional space, that along which M maintains the same value of potential of q. The plane of equipotential is orderly. The equation (7) of this curve is shown in [21]. The implication field is formed from a set of ordered equipotential

planes corresponding to the sequential successive values of q relative to the cardinalities $(n, n_A, n_B, n_{A\bar{B}})$ that would be varied [21].

$$q(A,\bar{B}) - \frac{n_{A\bar{B}} - \frac{n_A n_{\bar{B}}}{n}}{\sqrt{\frac{n_A n_{\bar{B}}}{n}}} = 0$$
(7)

3. Implication rules and association rules

A rule, denoted by $A \rightarrow B$, is a relation between a pair of sets (A, B). The examples (likelihood) of the rule are the objects identified by the antecedent A and the consequence B, while the counter-examples (unlikelihood) of the rule are the objects identified by A but negative B as Table 1 shows the relationship of components of rule.

Table 1. Contingency table for rule $A \rightarrow B$					
		В	\overline{B}	total	
	Α	n_{AB}	$n_{Aar{B}}$	n_A	
	\bar{A}	$n_{ar{A}B}$	$n_{ar{A}ar{B}}$	$n_{ar{A}}$	
	total	n_B	$n_{ar{B}}$	n	

A rule will have a better meaning when it has more examples and less counter-examples and vice versa. Likewise, a rule will be reinforced if the incremental component of the examples is faster than the incremental component of the counter-examples.

3.1. Association rules

An association rule is the simplification of a rule $A \rightarrow B$ in which A and B are two itemsets and $A \cap B = \emptyset$. The association rule is modelled as a mathematical model of four parameters n, n_A, n_B and a parameter of the distribution of both two variables such as n_{AB} [18]. Let \mathcal{R}_{ASS} be a set of all association rules; \mathcal{R}_{ASS} is presented by the following equation (8).

 \mathcal{R}_{ASS}

$$= (n, n_A, n_B, n_{AB}) \begin{vmatrix} n_A \leq n, n_B \leq n, \\ n_B \leq n, \\ \max(0, n_A + n_B - n) \\ \leq n_{AB} \leq \min(n_A, n_B) \\ (support \geq minsup, \\ confidence \geq minconf) \end{vmatrix}$$
(8)

The algorithm, named as $G\mathcal{R}_{ASS}$, is used to generate the set of association rules (\mathcal{R}_{ASS}). In $G\mathcal{R}_{ASS}$, we use the Apriori algorithm [19][20] and the thresholds of support and confidence (*minsup* and *minconf* respectively) to find the most useful rules. The main steps of this algorithm are:

Step 1: Finding the frequent itemsets (i.e. the sets of items that have minimum support)

Step 2: Using these frequent itemsets, the minimum confidence, and the minimum support to find rules

This algorithm limits the huge aggregation of itemsets, but it has some limitations as discussed above.



3.2. Implication rules

Implication association rule (referred to as *implication rule*) is also modelled by four parameters where the fourth one is the number of counter-examples $n_{A\bar{B}}$. Let \mathcal{R}_{IMP} be a set of all implication rules, \mathcal{R}_{IMP} is presented by the following equation (9).

$$\begin{aligned} \mathcal{R}_{IMP} \\ &= \left\{ (n, n_A, n_B, n_{A\bar{B}}) \middle| \begin{array}{c} 0 \leq n_A \leq n_B \leq n , \\ 0 \leq n_{A\bar{B}} \leq n_B \\ (support \geq minsupp, \\ confidence \geq minconf \\ SIA \ measure \ \Re \ threshold) \right\} \end{aligned}$$

Where \Re is " \leq " if the SIA measure belongs to the variance of the implication index measure, and \Re is " \geq " if the SIA measure belongs to the variance of the implication intensity measure. The SIA measure can be the implication index, the implication intensity, and their variations by the four parameters. In this paper, for the experiments, we use the variance of implication index by $n_{A\bar{B}}$.

SIA measures have the following properties [7] when compared to other probability and statistical measures:

- The implication index (and implication intensity) is an asymmetric and nonlinear statistical measure.

- The value of implication intensity increases with the size of the training set while other measures (support/confidence, lift, etc.) remain constant.

- The implication intensity reflects the way the human draws (removes) the previous statement. If a statement has strong implications, some counter-examples appear to be insufficient to change the implication of the rule. However, if the number of counterexamples appears more and more, the implication of the rule decreases; and eventually if the number of counter-examples is large enough, it will result in the elimination of the rule,

- The implication intensity is the good adaptation to noisy data, since a small number of counter-examples do not have the ability to invalidating the rule.

- The implication intensity does not allow the creation of rules such as $A \rightarrow B$ when *B* is true for almost all examples of the training set whether *A* is true or false. In that case, it is not surprising that the set with *A* to be true is almost included in the set with *B* to be true.

We developed the algorithm *IRG* to generate the set of implication rules (\mathcal{R}_{IMP}). *IRG* is similar to the algorithm used for association rules, but it also uses the statistical implication measures to constraint on rules. In this paper, we use the variance of implication index by n_{AB} (named as *if byCountExam*) for the experiment.

Algorithm 1. IRG (Implication Rules Generator)

Input: a dataset; the thresholds of confidence, support and a SIA measure; type of data (binary/quantitative).

Output: Implication rule set.

Step 1: Constructing a measure of variance in the implication index in the implication field by the counter-example. The proposed measure, named as

if byCountExam, is calculated as the follow.

if byCountExam =
$$q(A, \overline{B}) + \frac{1}{\sqrt{\frac{n_A(n - n_B)}{n}}}$$

Step 2: Generating the implication rules set from the dataset using a data mining algorithm (such as Apriori, Eclat, etc.) and the thresholds of support, confidence and *ifbyCountExam*. Note that: if data is in binary form, $q(A, \overline{B})$ is computed by equation (2); if the data is in quantitative form, $q(A, \overline{B})$ is computed by equation (4) and (3).

Step 3: Presenting each implication rules by four values $n, n_A, n_B, n_{A\bar{B}}$ as well as its values according to the measures such as support, confidence, implication index, implication intensity, and *if byCountExam*.

With the algorithm IRG, the generated implication rules will be more accurate because of the high examples (from support /confidence measures) and low counter-examples (from the statistical implication measure). This will be confirmed in the experimental section.

4. Recommendation

4.1. Based on association rules

The recommendation model based on the association rules $M_{\mathcal{R}_{ASS}}$ consists of: a dataset; the type of data (binary or quantitative data); the thresholds of support and confidence; the algorithm for generating the set of association rules (creating model); the algorithm for predicting and displaying the recommendation result. If dataset is in the quantitative form, it has to be binarized. $M_{\mathcal{R}_{ASS}}$ uses the algorithm $G\mathcal{R}_{ASS}$ (in Section 3) for generating the set of association rules \mathcal{R}_{ASS} . $M_{\mathcal{R}_{ASS}}$ is presented as the following equation (10).

$$M_{\mathcal{R}_{ASS}} \qquad dataset; \\ thresholds for support and confidence; \\ type of data; \\ algorithm G\mathcal{R}_{ASS} for generating \mathcal{R}_{ASS}; \\ algorithm for predicting \\ and displaying recommended result. \end{pmatrix} (10)$$

To predict and display the recommendation result to users, the recommendation model $M_{\mathcal{R}_{ASS}}$ uses \mathcal{R}_{ASS} and the algorithm similar to the algorithm *RBM1R* to be presented in Section 4.2.

4.2. Based on implication rules

Like $M_{\mathcal{R}_{ASS}}$, the recommendation model based on implication rule $M_{\mathcal{R}_{IMP}}$ not only includes the components presented in $M_{\mathcal{R}_{ASS}}$, but also uses SIA measures on binary or



quantitative dataset, and the algorithm *IRG* in Section 3.2 for generating the set of implication rules.

Another difference from $M_{\mathcal{R}_{ASS}}$, $M_{\mathcal{R}_{IMP}}$ can use a set of recommendation models, each of which corresponds to a SIA measure such as implication index, the implication intensity, or the variance of those measures.

The recommendation model based on implication rules $M_{\mathcal{R}_{IMP}}$ is presented as the following equation (11).

$$= X \begin{bmatrix} dataset; \\ thresholds for support, confidence; \\ SIA measure and its threshold; \\ type of data; \\ algorithm IRG for generating \mathcal{R}_i ; \\ algorithm for pedicting and \\ displaying recommended result. \end{bmatrix}$$

$$(11)$$

The recommendation model $M_{\mathcal{R}_{IMP}}$ is created by using the algorithm *RBMIR*. This algorithm is responsible for generating a set of implication rules and then recommending to users the appropriate items.

Algorithm 2. RBMIR (Recommendation by mining implication rules).

Input: a dataset; the thresholds of confidence, support and a SIA measure; type of data (binary/quantitative).

Output: 1 item or the list of top k items to be recommended to users.

Step 1: Calling the IRG algorithm for generating the set of implication rules.

Step 2: Predicting and returning the recommendation result (*1* item or *k* items) to users.

4.3. Evaluation of recommendation

Figure 3 illustrates the workflow to be used for evaluating the proposed systems. Firstly, the training set is used by the proposed algorithm ($G\mathcal{R}_{ASS}$ or IRG) to create a set of rules (a learned recommendation model). Secondly, that model uses the test set with known labels to make the prediction. Lastly, the prediction result and the test set with unknown labels are then compared by some of measures to generate the evaluation results.

To evaluate the accuracy of the list of useful items recommended to a user, we often compare the predicted items with the items already preferred by that user. Each item can be classified as True-Positive (TP), False-Positive (FP), True-Negative (TN), or False-Negative (FN) [8][23][28] as shown in Table 2. This matrix is often referred to as the confusion matrix.





Figure 3. Recommendation evaluation process.

Table 2. Confusion Matrix for recommendation systems				
	Recommended	Not Recommended		
Purchased	True Positive (TP)	False Negative (FN)		
Not purchased	False Positive (FP)	True Negative (TN)		

The measures such as TPR (True Positive Rate), FPR (False Positive Rate), precision, recall, and F_score (F1) [8][28][23] are used to evaluate the use of predictions. TPR is the percentage of purchased items that have been recommended. It is the ratio between the number of TP and the number of purchased items (TP + FN). FPR is the percentage of no purchased items that have been recommended. It is the ratio between the number of FP and the number of non-purchased items (FP + TN). The equations of precision, recall and F1 are shown in the following equations (12), (13) and (14) respectively.

$$precision = \frac{TT}{TP + FP}$$
(12)

$$recall = \frac{TP}{TP + FN}$$
(13)

$$F1 = \frac{2 \times Precision \times Recall}{Precision + Recall}$$
(14)

5. Experiment

The purpose of this experiment is to evaluate the performance and accuracy of the recommendation model based on implication rules and those of the recommendation model based on association rules (traditional ARM models). The SIA measure used by the experiment of this paper is the variation of the implication index in the implication field.

5.1. Data

We conduct the experiment on both binary dataset (MSWeb^{*}) and quantitative dataset (Movielens[†]). MovieLens collected by GroupLens is of 100,000 ratings given for 1682 films by 943 users. The ratings range from 1 (the lowest) to 5 (the highest). MSWeb is collected by listing all Vroots (the areas of the web site www.microsoft.com) that are visited by 38000



[†] https://grouplens.org/datasets/movielens/

anonymous, randomly-selected users in one-week timeframe. The datasets are pre-processed by normalizing and selecting relevant data to limit the bias, thereby to avoid overfitting problems as well as to get better accuracy.

We conduct the experiment in k-fold cross validation mode, with k=5. The steps of this mode is the follows: (1) Splitting the dataset (Movielens or MSWeb) into 5 equal sized parts; (2) Training on four parts and evaluating on the remaining one; (3) Repeating the second step by using different parts as the test set (the grey part):

Part 1Part 2Part 3Part 4Part 5Accuracy1Part 1Part 2Part 3Part 4Part 5Accuracy2Part 1Part 2Part 3Part 4Part 5Accuracy3Part 1Part 2Part 3Part 4Part 5Accuracy4Part 1Part 2Part 3Part 4Part 5Accuracy4Part 1Part 2Part 3Part 4Part 5Accuracy5

The quality of recommendation model is the average of 5 evaluations.

$$Accuracy = \frac{Accuracy_1 + \dots + Accuracy_5}{5}$$

5.2. Tools

We develop a tool in the R language. The tool consists of the proposed recommendation models and the utility functions to be used for this experiment.

5.3. Scenario 1: association rules vs implication rules on binary dataset

This scenario evaluates the accuracy of two recommendation systems IFARRS (based-on implication rules) and ARRS (based-on association rules) on binary dataset. IFARRS uses the recommendation model based on implication rules whereas ARRS uses the recommendation model based on association rules. In both systems, the number of items to be recommended to a user is 1, 5, 10, 20 and 25; and the thresholds of support and confidence are 0.1 and 0.3 respectively.

The comparison result is presented in Table 3 and Figure 4. They show that the precision, recall and the reconciliation between precision and recall (F1) of IFARRS is higher than those of ARRS as well as the false positive rate of IFARRS is lower than that of ARRS. However, the recall of IFARRS is lower than that of ARRS. Therefore, for systems where the precision, recall or F1 is important, we should use the model based on implication rules to make the recommendation.

Table 3. Experimental results accuracy of two models on binary dataset.

	Precision	Recall	F1	TPR	FPR
ARRS Model					
1	0.328	0.069243	0.338381	0.069243	0.003929
5	0.295771	0.303008	0.344725	0.303008	0.020587
10	0.248114	0.493032	0.32858	0.493032	0.043966
20	0.170629	0.666089	0.264644	0.666089	0.097064

25	0.147383	0.713444	0.238388	0.713444	0.124756		
IFARRS Model							
1	0.476525	0.101835	0.342267	0.101835	0.00305		
5	0.358738	0.364551	0.386516	0.364551	0.018452		
10	0.283955	0.518019	0.365517	0.518019	0.038844		
20	0.257943	0.609764	0.355118	0.609764	0.055464		
25	0.257419	0.611912	0.355015	0.611912	0.056025		



Figure 4. The ROC and Precision/Recall Curves of ARRS and IFARRS on MSWeb dataset

5.4. Scenario 2: association rules vs implication rules on quantitative dataset

This scenario is similar to Scenario 1, but it uses the quantitative dataset MovieLens. In both systems IFARRS and ARRS, the number of items to be recommended to a user is 1, 5, 10, 20 and 25; and the thresholds of support and confidence are 0.1 and 0.3 respectively.

The results in Table 4 and Figure 5 show that the accuracy (precision, recall, F1) of IFARRS is higher than that of ARRS; and the false positive rate of IFARRS is lower than that of ARRS. Therefore, for the quantitative datasets, we should use the implication rules based model to build the recommendation systems.

Table 4. Experimental results accuracy of two models on quantitative dataset.

	Precision	Recall	F1	TPR	FPR		
ARRS Model							
1	0.660177	0.01212	0.035563	0.0121202	0.001289		
5	0.581239	0.05052	0.095086	0.0505198	0.007996		
10	0.549381	0.093271	0.15272	0.0932714	0.017256		
20	0.503363	0.166315	0.229845	0.1663147	0.038238		
25	0.486442	0.19822	0.257257	0.1982202	0.049514		
IFA	IFARRS Model						
1	0.715044	0.014112	0.038154	0.0141123	0.001062		
5	0.638584	0.059556	0.109204	0.059556	0.006833		
10	0.588142	0.104618	0.168272	0.1046175	0.015663		
20	0.534956	0.181643	0.247681	0.1816426	0.035541		
25	0.51718	0.215541	0.276217	0.2155409	0.046224		





Figure 5. The ROC and Precision/recall Curve of ARRS and IFARRS models on Movielens dataset.

5.5. Scenario 3: the performance and recommendation time

This scenario is used for evaluating the performance (in terms of the size of the rule set) and the recommendation time (in term of the modelling time and the predictive time) of two recommendation systems IFARRS and ARRS.

Table 5 shows the result of both systems on MovieLens when the number of items to be recommended to a user is 5. The ratio between (the modelling time, the predicting time, the size of rule set) of IFARRS and those of ARRS is (0.4657, 0.6280, 0.0912) respectively. This demonstrates that the IFARRS on quantitative rules produces the better rule enforcement, has the faster recommendation time. This is result of the combination of the support and confidence measures for finding the rules with likelihood and the

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ifbyCountExam measure for filtering the rules with unlikelihood.

Table 5. Comparison of training time, predicting time and size of the rule set generated by the two models

No	Name	Modelling time	Predicting time	Size of rule
1	ARRS model	42.12367	10.58138	688536
2	IFARRS model	19.61867	6.645375	62796

6. Conclusion

The statistical implication analysis theory can be applied for building recommendation systems where the relationships among properties can be considered as implication rules. This paper proposes the implication rules based recommendation model on both binary and quantitative datasets. For the experiment, the proposed model uses the variance of the implication index in the implication field named as if byCountExam. The proposed model is compared with the association rule based recommendation model. The experimental results show that the proposed model increases the effectiveness of the recommendations: increasing the accuracy of recommended result, expanding the recommendations for quantitative data sets, as well as significantly reducing the number of rules to make the system faster and more efficient.

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